

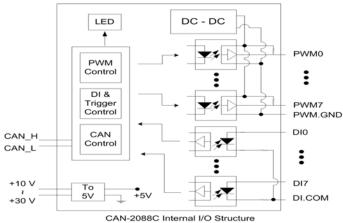
CAN-2088CImage: Point of the second seco

PWM (Pulse width modulation) is a powerful technique for controlling analog circuits. By using digital outputs, it can generate a waveform with variant duty cycle and frequency to control analog circuits. CAN-2088C, a CAN bus remote I/O modules with CANopen protocol, provides 8 PWM output channels and 8 digital inputs channels with high-speed counter function. It can be used to develop practical and economical analog control systems in the CANopen network.

Features

- Hardware-controlled PWM output.
- PWM output frequency: $0.2 \text{ Hz} \sim 500 \text{ kHz}$ with $0.1\% \sim 99.9\%$ duty cycle.
- PWM Output Modes: software trigger / hardware trigger.
- Trigger each PWM output individually or all PWM outputs synchronously.
- Support Burst output mode and Continue output mode.
- Provide 32-bit 500 kHz high-speed counter for each DI channel.
- Pass the validation of CANopen conformance test.
- Provide EDS file for CANopen master interface.

Block Diagram



	-	Pin Assignment PO.0	Output Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0	
<u> </u>	1.14	10500		Relay On	Relay Off	
- C		P0.1	Drive Relay	DO X PO.GND		
Č.		PO.2				
2		PO.3			* [001]1-000	
50	05	PO.4	_			
2	06	PO.5	Resistance Load		†⊡x □⊖ PO X	
20	07	PO.6				
0	08	PO.7		1001 32 VOA 32		
60	09	PO.GND	Input Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0	
No C	10	PO.GND	Relay Contact	Relay On	Relay Off	
0	11	DI.0		+0 DI X	+00 DIX	
0	12	DI.1	Contact	Relay Close DE DI.GND	° T □⊖ DI.GN	
0	13	DI.2	TTL/CMOS	Voltage > 10 V	Voltage < 4 V	
		DI.3	Logic	Logic Power O Logic Level Low DI X DI SND	Logic Power Come Level Low DI X DI M	
<u> </u>		DI.4		Open Collector On	Open Collector Off	
		DI.5	NPN Output			
20	17	DI.6	Output			
2 e	18	DI.7	-	Open Collector On	Open Collector Off	
20	19	DI.GND	PNP Output		* 	

CAN Pin & Baud Rate Rotary

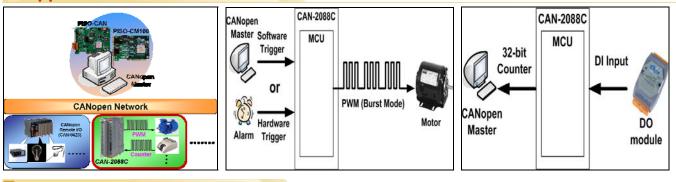
			Switch Value	Baud Rate	
CAN V+	Pin 5	200	0	10 kbps	
		ABOOTT	1	20 kbps	
	Pin 4		2	50 kbps	
CAN_Shield	Pin 3	1342°	3	125 kbps	
	Pin 2	Baud rate	4	250 kbps	
		rotary switch	5	500 kbps	
CAN_GND	Pin 1	IULALY SWILCH	6	800 kbps	
			7	1000 kbps	



Hardware Specifications

CAN Interface					
Connector	5-pin screwed terminal block (CAN_GND, CAN_L, CAN_SHLD, CAN_H, CAN_V+)				
Baud Rate (bps)	10 k, 20 k, 50 k, 125 k, 250 k, 500 k, 800 k, 1 M				
Terminator Resistor	Switch for 120 Ω terminator resistor				
Node ID	1~99 selected by rotary switch				
Protocol	CANopen DS-301 ver4.02, DS-401 ver2.1				
No. of PDOs	10 Rx, 10 Tx (support dynamic PDO)				
PDO Mode	Event Triggered, Remotely requested, Cyclic and acyclic SYNC				
Error Control	Node Guarding protocol and Heartbeat Producer protocol				
Emergency Message	Yes				
PWM Interface					
Channels	8 (Source)				
Frequency Range	$0.2 \text{ Hz} \sim 500 \text{ kHz}$ (non-continuous, the min. unit of the high/low level signal is 1 us).				
PWM Mode	Continue mode, Burst mode, Hardware trigger mode, Software trigger mode				
ESD Protection	4 kV Contact for each channel				
DI Interface					
Channels	8 (Sink)				
Counter Frequency	32-bit, 500 kHz Max.				
ESD Protection	4 kV Contact for each channel				
LED					
Round LED	PWR LED, RUN LED, ERR LED				
I/O LED	8 LEDs as PWM, 8 LEDs as Digital Input, and 1 LED as terminal resister indicator				
Power					
Input range	Unregulated $+10 \sim +30 \text{ V}_{DC}$				
Power Consumption	3.5 W				
Mechanism					
Installation	DIN-Rail				
Dimensions	32.3 mm x 99 mm x 77.5 mm (W x L x H)				
Environment					
Operating Temp.	$-25 \sim +75$ °C				
Storage Temp.	$-30 \sim +80$ °C				
Humidity	10 ~ 90% RH, non-condensing				

Applications



Ordering Information

CAN-2088C

CANopen Module of 8-channel PWM and 8-channel DI with High-speed Counters.